

Prediction of protein–protein interactions by docking methods

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Recently, developments have been made in predicting the structure of docked complexes when the coordinates of the components are known. The process generally consists of a stage during which the components are combined rigidly and then a refinement stage. Several rapid new algorithms have been introduced in the rigid docking problem and promising refinement techniques have been developed, based on modified molecular mechanics force fields and empirical measures of desolvation, combined with minimisations that switch on the short-range interactions gradually. There has also been progress in developing a benchmark set of targets for docking and a blind trial, similar to the trials of protein structure prediction, has taken place.

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Current Opinion in Structural Biology 2002, 12:28–35

0959-440X/02/\$ – see front matter

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Abbreviations

| | |
|------|--------------------------------|
| ACE | atomic contact energy |
| BD | Brownian dynamics |
| FFT | fast Fourier transform |
| GA | genetic algorithm |
| MD | molecular dynamics |
| NOE | nuclear Overhauser enhancement |
| PDB | Protein Data Bank |
| rmsd | root mean square deviation |

Introduction

In this review, we survey recent developments in those techniques that aim to predict the structure of a protein–protein complex in atomic detail, starting from the atomic coordinates, determined by X-ray crystallography or NMR spectroscopy, of the separate components ('unbound') (the related problems of protein–DNA interactions will not be discussed). Protein–protein interactions play a central role in biochemistry, because the formation of the complex has a functional consequence (e.g. signal transduction). The task of predicting the structure of the complex is one that we are not infrequently faced with, because of difficulties in crystallising complexes; of the more than fifteen thousand files in the Protein Data Bank (PDB), many of which are able to form protein–protein complexes, there are only a few hundred nonobligate protein–protein complexes. (Obligate complexes are permanent multimers whose components are not capable of independent existence.) Accurate predictive docking methods could therefore provide substantial structural knowledge about complexes, from which functional information could be inferred or experiments designed to obtain it. Most development has

been, and continues to be, targeted towards those complexes for which the conformational change on docking is fairly small, thus enabling the use of methods that are based on shape and chemical complementarity of the unbound components. This can be considered the 'canonical case' of protein–protein docking and will be the focus of this review.

The character of the interfaces in known protein–protein complexes has been thoroughly investigated in several reviews [1–3]. Whilst obligate complexes do have an interface that is slightly more hydrophobic than the rest of the molecular surface, there is very little indication of this in nonobligate complexes. The subset of complexes for which both components have been crystallised separately unbound provides the main test-bed for developments in protein–protein docking methods. There are about 30 of these complexes and the majority are in the protease–inhibitor or antibody–antigen class. The relative sizes of backbone and sidechain conformational changes on binding have been studied [4], and the protease–inhibitor and antibody–antigen complexes compared [5]. These and many other important classes of complexes, as well as the thermodynamics and kinetics of their formation, are discussed in a recently published book on protein–protein recognition [6*].

There are two parts to the docking problem: developing a scoring function/energy function that can discriminate correctly or near-correctly docked orientations from incorrectly docked ones, and developing a search method that will be able to 'find' a near-correctly docked orientation with reasonable likelihood. The simplest, yet still powerful, scoring function is shape complementarity. To use this, it is necessary to describe the surface shape of the protein. This may be done by discretising the molecule onto a grid in space and considering which cells ('voxels') are occupied, or by using some sort of 'surfacing algorithm', which calculates the solvent-accessible or solvent-excluded surface, and a point set that triangulates it. In carrying out this calculation, many special cases of geometry need to be considered [7,8]. The triangulation reflects the geometry of the surface: surface critical points (extrema), normals and curvature. In [9*], the distinction is drawn between this type of 'shape-explicit' method and 'shape-implicit' methods, which use only the occupied voxels to define the shape of the molecule.

But shape complementarity, although sufficient to recombine the separated components of a known complex, is not usually sufficient to dock unbound components. From a thermodynamic point of view, the native complex is at the global minimum of ΔG , the free energy change (ΔG) of formation of the complex relative to its separated components (usually taken to be unique, though there may, in rare cases, be more than one mode of binding [10]). The calculation

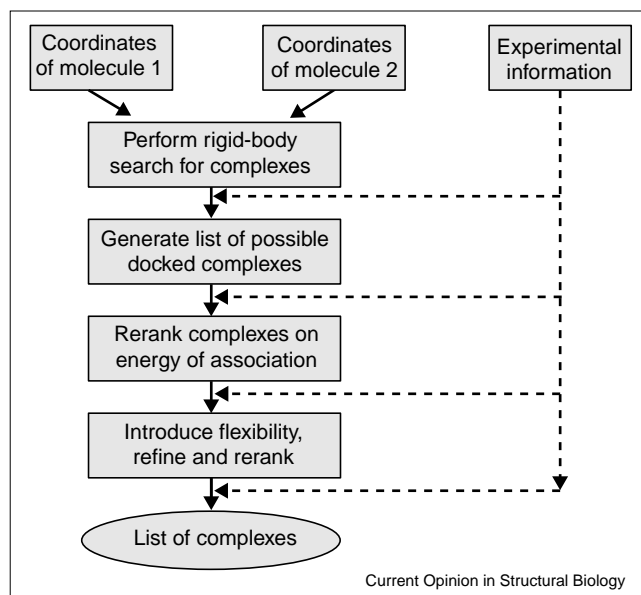
of ΔG is complicated and still the subject of research. As well as the direct electrostatic and van der Waals interactions between the proteins, there are water-mediated interactions; these affect the electrostatics via the dielectric effect and also produce the ‘hydrophobic effect’, primarily entropic in origin.

The role of electrostatics in protein–protein interactions has been reviewed by Sheinerman *et al.* [11] and Tobias [12], and was explored from a more physical point of view by Elcock *et al.* [13•]. To treat the desolvation of charged groups in the interfaces accurately, it is necessary to solve the full Poisson–Boltzmann equation for each different orientation of the components that is to be examined. This is an expensive calculation and so various approximation schemes are used: these include the ‘semi-Coulombic’ or ‘test charge’ approximation, or the use of Coulomb’s law with a distance-dependent dielectric, for example, proportional to r . Then, to any of these schemes may also be added an expression for the hydrophobic energy. Though theoretically complicated, it is found empirically to be approximated as a sum of the form $\gamma_i A_i$, where A_i is the solvent-accessible or solvent-excluded area of atom type i [14]. A further developed version of this, parameterised from contacts in protein interiors, is the ‘atomic contact energy’ or ACE [15]. There are also the dispersion and hard-core interactions, described by standard Lennard–Jones potentials.

Some ‘softening’ of the energy function is required (a removal of the divergences that electrostatic and Lennard–Jones energies have at $r=0$), otherwise, even in near-native dockings, these overwhelm the complementarity that remains. However, this softening necessarily reduces the capacity of the energy function to discriminate the correctly docked orientation from incorrect dockings, producing the many false positives that bedevil docking algorithms.

In practice, then, the above considerations frequently lead to a two- or three-stage approach to docking, as outlined in Figure 1. One begins by treating the proteins as rigid bodies, perhaps with some surface softness, searching the comparatively small (six-dimensional) space of relative protein orientations (translational and rotational) and identifying a set of candidate structures using some simple scoring function, with shape complementarity playing a major role. Then these structures are rescored using a more expensive energy function that is better at discriminating near-native orientations. In the third stage, we deal explicitly with a model in full atomic detail (if we did not before) and allow movement of the sidechains and possibly backbone, minimising a (possibly yet more complicated) energy function. The second and third stages may be combined. The energy/score landscape is rough and so it is clearly desirable to make the search as effective as possible by the use of efficient optimisation algorithms [16,17]. If extra biological information about the location of the interface is available, it can also be used as early as possible to simplify the search. Many of these considerations apply

Figure 1



The stages of protein–protein docking.

to methods for docking small-molecule ligands to proteins and any developments will be mentioned if they may be relevant to protein–protein docking.

First stage of docking: global search

One widely used technique in the first stage of docking is the fast Fourier transform (FFT) method. In the FFT method, the molecules are discretised onto a voxel grid. It uses the fact that, if the interaction (scoring function) between the molecules can be put into the form [18]:

$$\sum_{ij} p_i q_j \text{ or } \sum_{ij} p_i G(r_{ij}) q_j$$

then the score can be evaluated for all relative translations of the molecules in only $O(N^3 \ln N)$ operations (where N is the size of the grid). It is still necessary to search the three-dimensional space of relative orientations, which is usually done exhaustively. The functional forms given allow the approximate evaluation of electrostatic energies (the full Poisson–Boltzmann equation cannot be correctly solved) and shape complementarity using step functions that penalise overlaps between the cores of the molecules, but favour orientations in which the occupied voxels of one molecule lie in a ‘surface layer’ just outside the other.

This approach was first used in molecular docking by Katchalski-Katzir, Vakser and co-workers [19] and subsequently in the programs FTDock [20], 3D-Dock [21], GRAMM [22] and ZDOCK. It has proved successful in blind trials of protein docking [23]. More recently, it has been used in the program DOT [24•] and in work on identifying binding sites [25]. DOT uses 50 000 relative rotations and a 1 Å grid spacing, though 10 000 rotations

are normally used with FTDock/3D-Dock. In the unbound case, a surface ‘softness’ of the order of 2 Å can often be used. Very low resolutions may be used and still enable the interface region to be identified if the trial solutions are spatially clustered afterwards [26], though the correct relative orientation of the components is unlikely to be found in this case.

A significant new technique was introduced by Ritchie and Kemp [27•] in their program HEX — an expansion of the molecular surface and electric field in spherical harmonics. Fourier correlations between the expansion coefficients are used to simplify the problem of calculating the complementarity between the surfaces in different orientations to that of look up in a table of precalculated overlap integrals.

Another new method has been developed by Palma *et al.* [28•] in their program BIGGER, a surface-implicit method in which the surfaces are discretised and represented by values of 0 and 1 on two grids, the surface and core grids. These are then combined in real space, but high speed can be achieved by using fast bit-manipulation routines, as a single integer variable can hold many voxels.

Geometric hashing [29] is a shape-explicit algorithm. Surface critical points on one molecule (the ligand) are used to define local coordinate frames, in which the positions of nearby critical points are used as indices in a hash table, which stores the current coordinate frame. The process is then repeated for the other molecule (the receptor), the local coordinate frames are superimposed and the positions of the critical points near to the receptor are used to look up the corresponding ligand reference frames in the hash table of the ligand. A large number of correspondences to a particular frame indicates a strong local similarity in the shape of the surfaces, which is then checked. Again, when docking unbound proteins, a surface ‘softness’ must be used, corresponding to a ‘tolerance’ of about 1.5 Å in the coordinates. Searching is replaced by table look up, so the method is very fast. A recent development of this has been provided in [9•].

Two groups have published methods using optimisation of a real-space search with a genetic algorithm (GA) [30•,31•]. In [31•], the protein is represented by a solvent-accessible surface with normals, surface curvature and associated hydrogen-bonding character. The scoring function uses surface area, complementarity of curvature and normals, and penalises overlap of protein interiors. In [30•], a highly physically detailed scoring function, the Charmm molecular mechanics force field, is used from the beginning. In both cases, the ‘chromosome’ of the GA consists of the relative positions and orientations of the molecules (six ‘genes’).

Second stage of docking: rescoring

We now have typically a few hundred or thousand docked complexes after the first stage. We find, for example, that,

using FTDock/3D-Dock to dock unbound components, the largest surface complementarity score of an incorrect docking is typically around 1.5–2 times as great as the score of the complex that has the lowest rmsd from the crystallographic complex.

One method of rescoring is to use the statistics of residue–residue contacts across the interfaces of complexes in the PDB to define ‘statistical potentials’ expressing how much more probable it is that residues will interact than would be expected merely from random contacts between residues with the observed global frequencies of occurrence. The actual contacts in a complex can then be used to rescore it. In [32], such potentials were calculated using a few hundred nonhomologous nonhomodimeric protein–protein interfaces. Results were derived for residue–residue contacts and for atom–atom contacts of different chemical types, with the residue potentials proving the more powerful. Similar methods were used in [33], though with differences in the interfaces and random model, and in [34•], in which specific versions of the potentials were derived for the special case of antibody–antigen binding. Similar calculations are used to derive effective potentials between atom types for ligand–protein docking [35]

Other terms used in rescoring are electrostatics, hydrogen bonding [36], desolvation, lack of buried charges and physical unity of the interface. These were used in [28•,34•] and in the work of Vajda, Camacho and co-workers, who have concentrated not on the initial search, but on algorithms for rescoring complexes [37•] and refining them (see below). The different rescoring terms are commonly applied as a series of sequential filters or, as in [28•], combined with weights found by a neural network.

Third stage of docking: introduction of flexibility

At this stage of docking, the rigid-body approximation is abandoned and flexibility is introduced, at least in the protein sidechains and possibly in the backbone too. A molecular mechanics force field is normally used for the protein; water is still not usually explicitly included, but extra electrostatic/desolvation terms may be included instead.

As sidechain rearrangements dominate many docking problems, a common way to simplify the search is to restrict it to sampling just the known populated rotamers of the sidechains. Even so, the number of combinations of rotamers to be tested is usually too large to tackle exhaustively. One method is to use an iterative mean-field approach [38]. More recently, it has been proposed to prune the list of rotamers with dead-end elimination and then tackle the rest by either a branch-and-cut algorithm or a faster heuristic tree-based algorithm [39•]. Algorithms of this sort are also used in some ligand–protein docking algorithms, such as FlexE [40] and Dock 4.0 [41]. GAs are also well suited to the problem [42]. We remark that programs designed for protein–ligand docking can be used for the

Table 1**Programs for protein–protein docking.**

| Program* | Algorithm | Laboratory | URL | Details |
|--------------------------|---|--|--|--|
| Downloadable | | | | |
| 3D-Dock | Global: FFT; rescoring: residue potentials; refinement: mean-field sidechain multicopy | Imperial Cancer Research Fund/Imperial college (Sternberg) | www.bmm.icnet.uk/docking/ | Free to academic; distribution mostly source code (C); refinement sgi/linux executables |
| HEX | Global: Fourier correlation of spherical harmonics | Aberdeen University (Ritchie) | www.biochem.abdn.ac.uk/hex/ | Free to academic; sgi/sun/linux executables |
| GRAMM | Global: FFT clustering and rescoring decoys also available | SUNY/MUSC (Vakser) | reco3.ams.sunysb.edu/gramm/ | Free to academic; sgi/sun/ibm/dec/linux/win32 executables |
| PPD | Global: geometric hashing; rescoring: multiple filters | Columbia (Honig) | ftp://flash62.bioc.columbia.edu/pub/other | Free to academic; sgi executables |
| DOT | Global: FFT for shape complementarity and approximate Poisson–Boltzmann electrostatics | University of California San Diego (Ten Eyck) | www.sdsc.edu/CCMS/DOT | Free to academic; parallelised under mpi; source (C/fortran) and sun/sgi/dec/ibm executables |
| BIGGER (Chemera) | Global: bit mapping; rescoring: multiple filters | Universidade Nova de Lisboa | www.dq.fct.unl.pt/bioin/chemera/ www.biotechnol.com/Paginas/Chemera.htm | Free to academic; win32 executables |
| MERL refinement protocol | Constrained minimisation desolvation | University of Boston (MERL) (Vajda) | engpub1.bu.edu/bioinfo/MERL/software/decoys.html | Free; Charmm input scripts, source code (f77) |
| <i>DOCK</i> | Global: grid-based energy function; flexible docking: random search plus incremental construction | University of California San Francisco (Kuntz) | www.cmpharm.ucsf.edu/kuntz/dock.html | Free to academic; sgi executables |
| <i>AutoDock</i> | Grid-based empirical potential flexible docking via Monte Carlo search and incremental construction | Scripps Institute (Olson) | www.scripps.edu/pub/olson-web/download.html | Free to academic; source code and executables for sgi/dec/sun |
| <i>FlexX</i> | Fragment assembly energy function: (Boehm potential) | GMD-SCAI (Lengauer) | cartan.gmd.de/flexx/ | Licence required from Tripos.com |

Contact authors

| Program | Algorithm | Laboratory | Contact |
|---------|---|-----------------------------|---|
| DARWIN | GA Charmm force field | University of Pennsylvania | burnett@wistar.upenn.edu |
| ZDOCK | FFT for complementarity, electrostatics and residue potential | University of Boston (Weng) | sullivan.bu.edu/~rong/dock/download.shtml |

*Programs given in italics are designed principally for protein–ligand docking, but may be usable in the protein–protein case. Programs for MD, BD and continuum electrostatics calculations are also useful.

protein–protein problem (e.g. [43]), though there has been no systematic comparison.

Recent work by Vajda's group [37,44••] appears to have been a notable advance. An algorithm has been developed that, by concentrating on the reduction of the roughness due to van der Waals interactions and then controlling its re-introduction as docking proceeds, seems to converge reliably from an initial rmsd of 10 Å, which may be commonly produced by docking algorithms, to 2 Å, which is enough for accurate structural studies.

Larger conformational changes than the above mentioned have generally not been tackled successfully by docking. However, the most common known class of larger conformational changes (48 out of 100 entries in the

Database of Molecular Movements [45]) is the class of hinge-like interdomain movements. An algorithm capable of tackling this problem was described in [46], but seems not to have been tested beyond initial investigations on the reassembly of bound ligand–protein complexes.

Filtering

By this, we mean the use of biological information to constrain the structure of possible complexes. Though we have deferred discussion until now, it can be used early in docking. Commonly, it is known that some specific residues must lie in the interface, either because of the type of complex (e.g. one of the partners may be an antibody, in which case we know that at least some of the complementarity-determining regions must be involved) or as a result of mutagenesis information. Provision is made

Figure 2

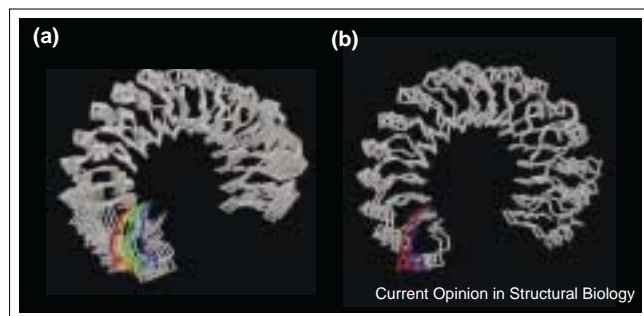


Figure comparing (a) the unbound structure of ribonuclease inhibitor and projections along the lowest eigenvector from principal components analysis of MD simulations with (b) the unbound (red) and bound (blue) X-ray structures of the inhibitor (PDB codes 2bnh and 1dfj, respectively). The coloured region forms the majority of the interface with the ribonuclease.

to use filtering information of this kind in programs such as 3D-Dock and HEX.

It is also possible to use the ‘natural mutagenesis’ information available from the alignment of homologous proteins to extract similar information; this has been the subject of much recent work, covered in detail in the reviews by Lichtarge and Sowa (pp 21–27) and by DeLano (pp 14–20) in this section. Generally, a cluster (‘hot spot’) of conserved residues, particularly polar residues, identifies a binding site with some confidence ([47•,48]; reviewed in [49]). Use of this information is aided by the concomitant development of structural alignment programs [50].

An interesting example of detailed constraints for filtering is that which comes from NMR spectroscopy of the complex. Even a small number of nuclear Overhauser enhancements (NOEs) and dipolar couplings (a few tens) suffice to determine the structure of the complex completely to high precision if the unbound components are also known. This is a sufficiently common and useful case that three similar studies have been carried out recently [51•,52•,53], using docking programs modified to take the NMR constraints as additional input. One of these methods [52•] can work with an unassigned ^1H spectrum, rather than NOEs, but has not been tested on unbound components.

Many of the programs described above are available to the community for their own research. Because they are computationally intensive, they must be downloaded from the World Wide Web and run on the user’s own computer. Table 1 provides a list of many of the available programs.

The physics of docking: kinetics and funnel landscapes

The docking algorithms mentioned above do not generally reflect the physical process of docking. The picture

emerging (see the review by Schreiber [pp 41–47] in this section and also [54,55]) is first of a diffusional search and then the formation of an ‘encounter complex’, which passes through some intermediate states of increasing desolvation to the docked complex. In the diffusional search, it is well known from kinetics studies that components that have charge complementarity and a strong dipole associate much faster than would be expected from random diffusional encounters. This is most readily visualised simply as a ‘funnel’ in the spatial and orientational degrees of freedom, directing the incoming component towards the interface that will bind it and orientating it correctly. Desolvation may help here too [56]. A common way to simulate this process is Brownian dynamics (BD) [57] (see the review by Elcock *et al.* [13•] and the forthcoming review in this journal by Gabdoulline and Wade [58]). BD simulations have, in the past, used a simplified model of proteins, but recently full atomistic simulations have been introduced, which, though requiring an empirical definition of when the encounter complex is formed, give very good agreement with experiment ([59•] reviews recent work). Some studies have gone beyond the encounter complex, using surface area and ACE desolvation terms [60•].

As the components approach and sidechains begin to rearrange, the ‘binding funnel’ changes from an object in low-dimensional (Cartesian) space. It becomes more complex, with more dimensions, corresponding to the flexible sidechain and backbone movements, and more rugged, as desolvation forces and finally van der Waals forces dominate over the smoothly changing electrostatics. The structure of this part of the funnel has been investigated by Zhang *et al.* [43]. This ‘binding funnel’ has been the subject of several other discussions. In [61], it is predicted that proteins that have a rougher energy landscape will be more promiscuous in their binding. The binding funnel is linked conceptually to the ‘folding funnel’ of modern protein folding theory via a discussion of disorder/order transitions. The success of the refinement method [44••] described above suggests that this close-range binding funnel remains if the energy function is modified.

In recent work from Vakser’s group [62], the spatial distribution and clustering of high-scoring orientations generated by their GRAMM docking program are used to define those proteins for which the docking landscape has a funnel. A majority (about 70%) of the complexes have a funnel-like landscape by this criterion.

Do the conformational changes on docking reflect the conformational flexibility shown by the isolated components? Molecular dynamics (MD)-based work focusing on the sidechain movements of the unbound components of four complexes has been carried out [63•]; it was found that there is some tendency to move towards the conformations found in the complex. We have been engaged in related work (GR Smith, MJE Sternberg, unpublished data) and included small backbone conformational changes. We

performed a principal components analysis of 1 ns duration MD trajectories and compared the eigenvectors of lowest frequency, describing conformational changes, with the known conformational changes on docking, using a sliding window along the protein backbone. We found appreciable overlap in many cases; an example that works particularly well is the ribonuclease inhibitor (PDB code 2bnh). In this case, the inner product and overlap of the first MD eigenvector, and the known conformational change (over an eight-residue moving window) in the interface region of the inhibitor 2bnh is very high at 0.78 (with a peak of 0.99). This indicates that the chains are moving in the same direction, as shown in Figure 2. This result suggests that the conformational changes reflect the natural conformational propensities of the unbound components, for some complexes at least.

Future directions and conclusions

The protocol of fast docking followed by rescoring and refinement is well established, and is effective in many cases of small conformational change upon docking, especially if biological information is available. Without this information, it is still discouragingly difficult to get the near-native complex from unbound components at top rank and we still tend to settle for a good chance of getting one in the top ten (say). New fast methods for the initial docking have been developed and there have been advances in methods for rescoring and refinement. Ideas from the kinetics of binding and the role of binding funnels provide insight, and are already beginning to have a practical effect on docking algorithms. In particular, by emphasising the generation of docked complexes using surface complementarity followed by rescoring, the ‘classical’ methods may make the refinement stage more difficult by forcing it to be carried out in the part of the search space dominated by many deep local minima due to van der Waals interactions between the components.

Turning from highly accurate and computationally expensive modelling to cases in which speed is more important, the flow of data from structural genomics projects over the next few years will also provide a challenge to docking. Probably, relatively few complexes will be solved, but data about interactions (albeit with large numbers of false positives and negatives) will come from, for example, high-throughput yeast two-hybrid screens. It will be useful to try to make sense of this data by docking the components or homology models of them (as structural genomics should make many globular proteins accessible to homology modelling). However, at the moment, only preliminary work has been carried out even on testing the performance of docking programs when docking homology models of varying degrees of accuracy.

The guidance of docking by the inclusion of the increasing amount of data available on protein–protein interactions (as reviewed in this section), for example, to give information on binding sites, interaction partners and conformational changes, will also be important.

Docking approaches to protein interactions will ultimately need to be placed in the context of the cell, where the promiscuity of interactions, the role of crowding [64] and the occurrence of weak (approximately millimolar) interactions that are nevertheless of great biological importance will need to be addressed. An examination of weak docking interactions using BD has recently been made [65]. The role of water in interfaces [2,66] also requires further investigation, if the fine details of sidechain contacts are to be reproduced. Clearly, however, the lack of explicit water does not prevent a correct prediction in many cases.

At a less speculative level, there has been some agreement on the need for the development of methods for the assessment of current docking procedures — agreed measures of the quality of a complex by rmsd or percentage of native contacts and so on — and the construction of a standard ‘test set’ of unbound components (see <http://sullivan.bu.edu/~rong/dock/benchmark.shtml>) and ‘decoy sets’ (false positives from docking) of various rmsd from the correct structure, but all passing the more obvious requirements of acceptable surface and electrostatic complementarity [67].

An arrangement is also being put in place for blind tests of docking methods when new protein–protein complexes are crystallised, under a similar protocol to the successful CASP (Comparative Assessment of Structure Prediction) assessment exercises (see <http://predictioncenter.llnl.gov>). The first such trial has recently taken place, on two antibody–viral receptor complexes and one kinase–substrate complex (see <http://capri.ebi.ac.uk>). Groups took part using many of the protein–protein docking programs described above, as well as protein–ligand docking programs. Trials such as this are essential for the evaluation of the current status of computer methods to predict protein–protein interaction by docking.

Acknowledgements

GRS would like to acknowledge helpful e-mail communications with Adrian Elcock, Gideon Schreiber and Rebecca Wade.

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